

MATH 637: Mathematical Techniques in Data Science

Support vector machines and kernels

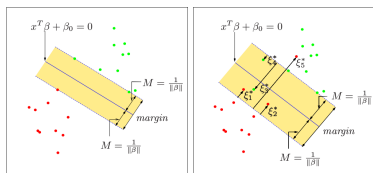
Dominique Guillot

Departments of Mathematical Sciences
University of Delaware

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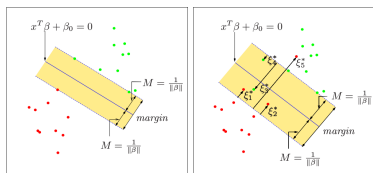
Separating sets: mapping the features

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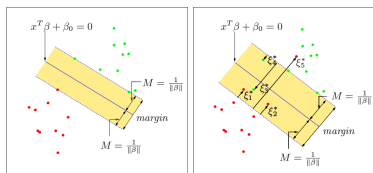
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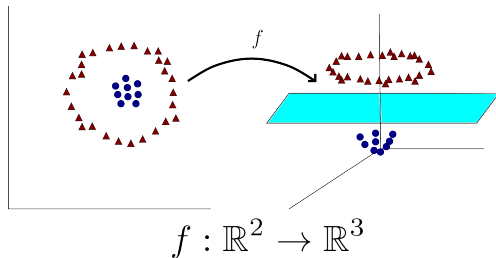
What if the data is not separable?

Separating sets: mapping the features

We saw in the previous lecture how support vector machines provide a robust way of finding a separating hyperplane:



What if the data is not separable? Can map into a high-dimensional space.



A brief intro to duality in optimization

Consider the (primal) problem:

$$\begin{aligned} & \min_{x \in \mathcal{D} \subset \mathbb{R}^n} && f_0(x) \\ & \text{subject to} && f_i(x) \leq 0, \quad i = 1, \dots, m \\ & && h_i(x) = 0, \quad i = 1, \dots, p. \end{aligned}$$

Denote by p^* the optimal value of the problem.

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Lagrangian: $L : \mathcal{D} \times \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$

$$L(x, \lambda, \nu) := f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x).$$

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$$g(\lambda, \nu) := \inf_{x \in \mathcal{D}} L(x, \lambda, \nu).$$

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Claim: for every $\lambda \geq 0$,

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Proof. Assume \tilde{x} satisfies the constraints and $\lambda \geq 0$. Then

$$f_0(\tilde{x}) \geq L(\tilde{x}, \lambda, \mu) \geq \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) = g(\lambda, \mu).$$

The result follows by optimizing over \tilde{x} .



Dual problem:

$$\begin{aligned} & \max_{\lambda \in \mathbb{R}^m, \nu \in \mathbb{R}^p} g(\lambda, \nu) \\ & \text{subject to } \lambda \geq 0. \end{aligned}$$

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Strong duality: $d^* = p^*$.

- Does not hold in general.
- Usually holds for convex problems.
- (See e.g. Slater's constraint qualification).

The kernel trick

Recall that SVM solves:

$$\min_{\beta_0, \beta, \xi} \frac{1}{2} \|\beta\|^2$$

subject to $y_i(x_i^T \beta + \beta_0) \geq 1 - \xi_i$

$$\sum_{i=1}^n \xi_i = C, \quad \xi_i \geq 0.$$

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The associated Lagrangian is

$$L_P = \frac{1}{2} \|\beta\|^2 + C \sum_{i=1}^n \xi_i - \sum_{i=1}^n \alpha_i [y_i(x_i^T \beta + \beta_0) - (1 - \xi_i)] - \sum_{i=1}^n \mu_i \xi_i,$$

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which we minimize w.r.t. β, β_0, ξ . Setting the respective derivatives to 0, we obtain:

$$\beta = \sum_{i=1}^n \alpha_i y_i x_i, \quad 0 = \sum_{i=1}^n \alpha_i y_i, \quad \alpha_i = C - \mu_i \quad (i = 1, \dots, n).$$

The kernel trick (cont.)

Substituting into L_P , we obtain the Lagrange (dual) objective function:

$$L_D = g(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j.$$

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$$\begin{aligned} (K(x_i, x_j)) &= (\langle h(x_i), h(x_j) \rangle) \\ &= (\langle v_i, v_j \rangle) \\ &= V^T V, \quad \text{where } V = (v_1^T, \dots, v_N^T). \end{aligned}$$

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Conclusion: the matrix $(K(x_i, x_j))$ is positive semidefinite.

Positive definite kernels (cont.)

- **Necessary condition to have $K(x, x') = \langle h(x), h(x') \rangle$:**

$$(K(x_i, x_j))_{i,j=1}^N \text{ is psd}$$

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Definition: Let \mathcal{X} be a set. A symmetric kernel $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is said to be a *positive (semi)definite kernel* if

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Theorem. Let \mathcal{X} and let $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ be a positive definite kernel on \mathcal{X} . Then there exists a Hilbert space \mathcal{H} and a map $h : \mathcal{X} \rightarrow \mathcal{H}$ such that

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Moral: Positive definite kernels arise as $\langle h(x), h(x') \rangle_{\mathcal{H}}$.

- A *reproducing kernel Hilbert space* (RKHS) over a set \mathcal{X} is a Hilbert space \mathcal{H} of functions on \mathcal{X} such that for each $x \in \mathcal{X}$, there is a function $k_x \in \mathcal{H}$ such that

$$\langle f, k_x \rangle_{\mathcal{H}} = f(x) \quad \forall f \in \mathcal{H}.$$

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- One can show that \mathcal{H} is a RKHS over \mathcal{X} iff the evaluation functionals $\Lambda_x : \mathcal{H} \rightarrow \mathbb{C}$

$$f \mapsto \Lambda_x(f) = f(x)$$

are continuous on \mathcal{H} (use Riesz's representation theorem).

Theorem: Let $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ be a positive definite kernel. Then there exists a RKHS \mathcal{H}_k over \mathcal{X} such that

- 1 $k(\cdot, x) \in \mathcal{H}_k$ for all $x \in \mathcal{X}$.
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Then

$$\langle h(x), h(x') \rangle_{\mathcal{H}_k} = \langle k(\cdot, x), k(\cdot, x') \rangle_{\mathcal{H}_k} = k(x, x').$$

We can replace h by any positive definite kernel in the SVM problem:

$$\begin{aligned}L_D &= \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{h}(\mathbf{x}_i)^T \mathbf{h}(\mathbf{x}_j) \\ &= \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{K}(\mathbf{x}_i, \mathbf{x}_j).\end{aligned}$$

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Three popular choice in the SVM literature:

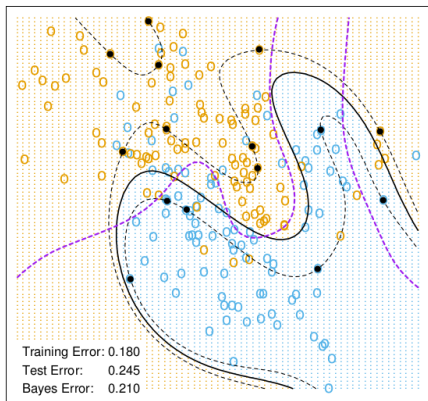
$$K(x, x') = e^{-\gamma \|x-x'\|_2^2} \quad (\text{Gaussian kernel})$$

$$K(x, x') = (1 + \langle x, x' \rangle)^d \quad (d\text{-th degree polynomial})$$

$$K(x, x') = \tanh(\kappa_1 \langle x, x' \rangle + \kappa_2) \quad (\text{Neural networks}).$$

Example: decision function

SVM - Degree-4 Polynomial in Feature Space



ESL, Figure 12.3 (solid black line = decision boundary, dotted line = margin).