MATH 637: Mathematical Techniques in Data Science Independent component analysis

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Motivation

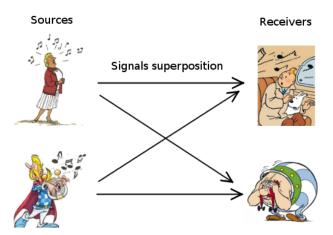
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We will therefore assume the sources are not Gaussian.

• We seek sources that are as independent as possible.

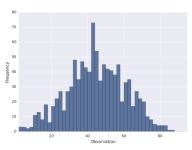
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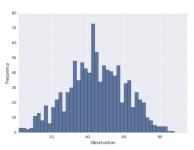
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To explain the above notions, we briefly discuss some concepts from *information theory*.

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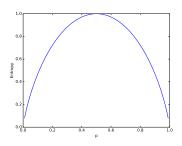
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Example: If X is a (discrete) uniform on $\{1, \ldots, N\}$, then

$$H(X) = -\sum_{i=1}^{N} \frac{1}{N} \log \left(\frac{1}{N}\right) = \log N.$$

Entropy (cont.)

Example: $X \sim \operatorname{Bernoulli}(p)$, i.e., P(X=1) = p, P(X=0) = 1 - p. The more "uncertain" the outcome is, the larger the entropy.



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The entropy of X is the average information "contained" in X:

$$H(X) = \sum_{i=1}^{N} I(p_i)p_i.$$

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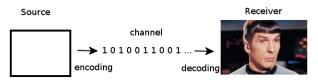


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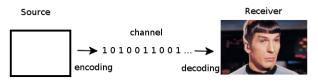
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- The entropy provides a **lower bound** on the average number of bits required per symbol.

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The KL divergence is used as a measure of distance between distributions (note however that $D_{\mathrm{KL}}(P||Q) \neq D_{\mathrm{KL}}(Q||P)$ in general).

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The mutual information of (X_1, \ldots, X_n) is given by

$$I(X_1,\ldots,X_n)=D_{\mathrm{KL}}(p(x_1,\ldots,x_n)||p(x_1)\ldots p(x_n)).$$

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- We have I(X,Y)=0 if and only if X,Y are independent.
- Therefore, $I(X_1,\ldots,X_n)$ provides a numerical measure of how independent random variables are.

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 Motivated by the fact that the Gaussian distribution has the largest entropy among all continuous distributions with a given mean and variance.

• The kurtosis (from greek κυρτός, "curved") of a random variable with mean $\mu=E(X)$ is given by

$$Kurt(X) := \frac{E[(X - \mu)^4]}{(E[(X - \mu)^2])^2}.$$

- Measures the "propensity to produce outliers".
- The Gaussian distribution has kurtosis equal to 3.
- Can thus use the "excess kurtosis" $\operatorname{Kurt}(X) 3$ to test for "non-Gaussianity".
- ullet The **negentropy** of a random variable X is given by

$$J(X) := H(X_{\text{gauss}}) - H(X),$$

where $X_{\rm gauss}$ is a Gaussian random variable with the same mean and variance as X.

- Motivated by the fact that the Gaussian distribution has the largest entropy among all continuous distributions with a given mean and variance.
- Therefore, a variable that is "far from a Gaussian" should have a larger negentropy.

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- The negentropy is replaced by the approximation

$$J(X) \approx [E(G(X)) - E(G(X_{\text{gauss}}))]^2,$$

where $G(x) = \log \cosh(x)$.

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• Next, we want the linearly transform the rows of X so that they become *uncorrelated*. We seek a linear transformation $L: \mathbb{R}^{N \times M} \to \mathbb{R}^{N \times M}$ such that

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• Define the whitened data matrix by

$$X_{\text{white}} := UD^{-1/2}U^TX.$$

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The FastICA algorithm:

- Find a first direction w_1 maximizing the (approximation of) the negentropy (can use a fixed point method).
- Estimate a second direction $w_2 \perp w_1$ maximizing the (approximation of) the negentropy.
- etc..

Python - example

We mix two sound files, and recover them using ICA.

```
import scipy.io.wavfile
import numpy as np
rate, data1 = scipv.io.wavfile.read('daft-punk.wav')
rate2, data2 = scipy.io.wavfile.read('weather.wav')
mix1 = np.int16(0.3*data1+0.5*data2)[:,0]
mix2 = np.int16(0.2*data1+0.4*data2)[:.0]
scipy.io.wavfile.write('./out/mix1.wav',rate,mix1)
scipy.io.wavfile.write('./out/mix2.wav',rate.mix2)
from sklearn.decomposition import FastICA
ica = FastICA(n_components = 2)
X = np.vstack([mix1,mix2]).T
S = ica.fit transform(X)
A = ica.mixing
# Rescale components to have approximately the same mean amplitude as the first mixed signal
m = abs(mix1).mean()
m1 = abs(S [:.0]).mean()
m2 = abs(S [:.1]).mean()
S1 = np.int16(S_[:,0]*m/m1)
S2 = np.int16(S \cdot \Gamma: .1]*m/m2)
scipy.io.wavfile.write('./out/estimated_source1.wav',rate,S1)
scipy.io.wayfile.write('./out/estimated source2.way'.rate.S2)
```