MATH 567: Mathematical Techniques in Data Clustering I

Dominique Guillet

Departments of Mathematical Sciences University of Delaware

May 1 2017

1/16

Supervised and unsupervised learning

Supervised learning problems:

- Data (X,Y) is "labelled" (input/output) with joint density P(X, Y).
- We are mainly interested by the conditional density P(Y|X).
- Example: regression problems, classification problems, etc... Unsupervised learning problems:

- Data X is not labelled and has density P(X).
- We want to infer properties of P(X) without the help of a "supervisor" or "teacher".
- Examples: Density estimation, PCA, ICA, sparse autoencoder. clustering, etc...

2/16

Clustering









- Unsupervised problem.
- Work only with features /independent variables.
- Want to label points according to a measure of their similarity.

We try to partition observations into "clusters" such that:

- Intra-cluster distance is minimized.
- Inter-cluster distance is maximized.



For graphs, we want vertices in the same cluster to be highly connected, and vertices in different clusters to be mostly disconnected.

The K-means algorithm

Goes back to Hugo Steinhaus (of the Banach-Steinhaus theorem) in 1957.



Steinhaus authored over 170 works. Unlike his student, Stefas Banach, who tended to specialize narrowly in the field of functional analysis, Steinhaus made contributions to a wide ange of matematical sub-disciplines, including geometry, probability theory, functional analysis, theory of trigonometric and Fourier series as well as mathematical lagic. He also wore in the area of applied mathematics and enthusinatically collibrated with engineers, geologists, economists, physicians, biologists and, in Kar's words. "Pene lawares".

Source: Wikipedia.

5/16

7/16

The K-means algorithm (cont.)

The K-means algorithm is a popular algorithm to cluster a set of points in \mathbb{R}^p .

- ullet We are given n observations $x_1, x_2, \ldots, x_n \in \mathbb{R}^p$.
- ullet We are given a number of clusters K.
- $m{ ilde{m{arphi}}}$ We want a partition $\hat{S}=\{S_1,\ldots,S_K\}$ of $\{x_1,\ldots,x_n\}$ such that

$$\hat{S} = \underset{S}{\operatorname{argmin}} \sum_{i=1}^{K} \sum_{x_i \in S_i} ||x_j - \mu_i||^2,$$

where $\mu_i=\frac{1}{|S_i|}\sum_{x_j\in S_i}x_j$ is the mean of the points in S_i (the "center" of S_i).

- The above problem is NP hard.
- Efficient approximation algorithms exist (converge to a local minimum though).

6/16

Lloyds's algorithm

Lloyds's algorithm for K-means clustering

- Denote by C(i) the cluster assigned to x_i .
- L byds's algorithm provides a heuristic method for optimizing the K-means objective function.

Start with a "cluster centers" assignment $m_1^{(0)}, \dots, m_K^{(0)}$. Set t := 0. Repeat:

lack a Assign each point x_j to the cluster whose mean is closest to x_j :

$$S_i^{(t)} := \{x_j : \|x_j - m_i^{(t)}\|^2 \le \|x_j - m_k^{(t)}\|^2 \ \forall k = 1, \dots, K\}.$$

lacktriangled Compute the average $m_i^{(t+1)}$ of the observations in cluster i:

$$m_i^{(t+1)} := \frac{1}{|S_i^{(t)}|} \sum_{x_j \in S_i^{(t)}} x_j.$$

 \bullet $t \leftarrow t + 1$. Until convergence.

Convergence of Lloyds's algorithm

Note that Lloyds's algorithm uses a greedy approach to sequentially minimize:

$$\sum_{i=1}^{K} \sum_{x_i \in S_i} ||x_j - m_i||^2.$$

- Both steps of the algorithm decrease the objective.
- Thus, Lloyds's algorithm converges a local minimum of the objective function.
 There is no guarantee that Lloyds' algorithm will find the global
- optimum.

 As a result, we use different starting points (i.e., different choices
- As a result, we use different starting points (i.e., different choices for the initial means $m_i^{(0)}$).
- Common initialization methods:
 - ullet The Forgy method: Pick K observations at random from $\{x_1,\ldots,x_n\}$ and use these as the initial means.
- Random partition: Randomly assign a cluster to each observation and compute the mean of each cluster.

Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Source (min 2/4) or decelibration com

9/10

Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Surrection 974 or decelebendane rank

9/16

Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Source (min 2/4) or decelibration com

9/16

Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Spring to a 274 partie of the artists com-

9/16

Illustration of the K-means algorithm

- 100 random points in \mathbb{R}^2 .
- The algorithm converges in 7 iterations (with a random centers initialization).



Example: clustering the zip data

Is there a nice cluster structure in the zip dataset?

- Experiment:

 Find 10 clusters using K-means.
 - ullet Compute the percentage p_{ij} of samples labelled i having "true" label j.

 $p_{ij} =$

0.00	0.00	2.45	0.38	0.94	0.57	0.00	83.96	0.19	11.51
14.78	0.00	0.77	0.26	0.77	14.40	68.64	0.00	0.39	0.00
1.08	0.46	7.57	11.13	0.77	10.66	0.31	0.62	66.46	0.93
90.37	0.00	2.28	0.18	0.18	1.23	5.08	0.00	0.70	0.00
88.96	0.00	0.51	0.34	0.00	2.72	7.13	0.00	0.34	0.00
1.08	0.00	86.15	1.85	2.15	1.38	5.54	0.31	1.54	0.00
1.41	0.00	5.66	1.13	62.23	5.66	1.41	3.25	1.41	17.82
1.63	0.00	3.69	59.22	0.00	32.00	0.00	0.00	3.25	0.22
0.00	93.03	0.37	0.09	3.90	0.00	0.84	0.28	1.02	0.46
0.00	0.12	1.10	1.46	16.93	0.61	0.24	20.46	4.99	54.08

Stores in pro/storide colitores (pre-scare) 0/16 10/16

Spectral clustering: overview

We saw how K-means can be used to cluster points in \mathbb{R}^p . Spectral clustering:

- Very popular clustering met hod.
- · Often outperforms other methods such as K-means.
- Can be used for various "types" of data (not only points in R^p).
- Easy to implement. Only uses basic linear algebra.

Overview of spectral clustering:

- Construct a similarity matrix measuring the similarity of pairs of objects.
- Use the similarity matrix to construct a (weighted or unweighted) graph.
- Compute eigenvectors of the graph Laplacian (builds an embedding of the graph into R^p).
- Cluster the graph using the eigenvectors of the graph Laplacian using the K-means algorithm.

11/16

Notation

We will use the following notation/conventions:

- ullet G=(V,E) a graph with vertex set $V=\{v_1,\ldots,v_n\}$ and edge set $E\subset V\times V$.
- ullet Each edge carries a weight $w_{ij} \geq 0$.
- ullet The adjacency matrix of G is $W=W_G=(w_{ij})_{i,j=1}^n$. We will assume W is symmetric (undirected graphs).
- The degree of v_i is

$$d_i := \sum_{j=1}^{n} w_{ij}$$
.

- ullet The degree matrix of G is $D:=\mathrm{diag}(d_1,\ldots,d_n)$.
- ullet We denote the complement of $A\subset V$ by \overline{A}
- If $A \subset V$, then we let $1_A = (f_1, \dots, f_n)^T \in \mathbb{R}^n$, where $f_i = 1$ if $v_i \in A$ and 0 otherwise.

12/16

Similarity graphs

ullet We assume we are given a measure of similarity s between data points $x_1,\dots,x_n\in\mathcal{X}$:

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We denote by $s_{ij} := s(x_i, x_j)$ the measure of similarity between x_i and x_j .
- ullet Equivalently, we may assume we have a measure of distance between data points (e.g. (\mathcal{X},d) is a metric space).
- Let $d_{ij} := d(x_i, x_j)$, the distance between x_i and x_j .
- ullet From d_{ij} (or s_{ij}), we naturally build a similarity graph.
- We will discuss 3 popular ways of building a similarity graph.

Similarity graphs (cont.)

Vertex set = $\{v_1, \dots, v_n\}$ where n is the number of data points.

- The -neighborhood graph: Connect all points whose pairwise distances are smaller than some
 ∈ > 0. We usually don't weight the edges. The graph is thus a simple graph (unweighted, undirected graph containing no loops or multiple edges).
- The k-nearest neighbor graph: The goal is to connect v_i to v_j if x_j is among the k nearest neighbords of x_i. However, this leads to a directed graph. We therefore define:
 - a the k-nearest neighbor graph: v_i is adjacent to v_j iff x_j is a mong the k-nearest neighbords of x_i OR x_i is a mong the k-nearest neighbords of x_i .
 - a the mutual k-nearest neighbor graph: v_i is adjacent to v_j iff x_j is among the k nearest neighbords of x_i **AND** x_i is among the k nearest neighbors of x_j .

We weight the edges by the similarity of their endpoints.

Similarity graphs (cont.)

• The fully connected graph: Connect all points with edge weights s_{ij}. For example, one could use the Gaussian similarity function to represent a local neighborhood relationships:

$$s_{ii} = s(x_i, x_i) = \exp(-\|x_i - x_i\|^2/(2\sigma^2))$$
 $(\sigma^2 > 0).$

Note: σ^2 controls the width of the neighborhoods.

All graphs mentioned above are regularly used in spectral clustering.

15/16

Graph Laplacians

There are three commonly used definitions of the graph Laplacian:

The unnormalized Laplacian is

$$L := D - W$$
.

The normalized symmetric Laplacian is

$$L_{\rm sym} := D^{-1/2} L D^{-1/2} = I - D^{-1/2} W D^{-1/2}.$$

The normalized "random walk" Laplacian is

$$L_{tw} := D^{-1}L = I - D^{-1}W.$$

We will see in the next lecture how these Laplacians can be used to cluster graphs.

16/16