

MATH 567: Mathematical Techniques in Data
Science
Linear Regression: old and new

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- In the example, we want:
price = $\beta_1 \cdot$ mileage + $\beta_2 \cdot$ cylinder + ...

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Modern setting:

- In modern problems, it is often the case that $n \ll p$.
- Requires supplementary assumptions (e.g. sparsity).
- Can still build good models with very few observations.

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$$Y \in \mathbb{R}^{n \times 1} \quad X \in \mathbb{R}^{n \times p}$$

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$$Y = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{pmatrix} \quad X = \begin{pmatrix} | & | & \dots & | \\ \mathbf{x}_1 & \mathbf{x}_2 & \dots & \mathbf{x}_p \\ | & | & \dots & | \end{pmatrix},$$

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- We want $Y = \beta_1 X_1 + \dots + \beta_p X_p$.
- Equivalent to solving

$$Y = X\beta \quad \beta = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_p \end{pmatrix}.$$

Classical setting (cont.)

We need to solve $Y = X\beta$.

- In general, the system has **no solution** ($n \gg p$) or **infinitely many solutions** ($n \ll p$).

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$$\hat{\beta} = \operatorname{argmin}_{\beta \in \mathbb{R}^p} \|Y - X\beta\|^2.$$

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$$\begin{aligned} 0 &= \frac{\partial}{\partial \beta_i} \|Y - X\beta\|^2 = \frac{\partial}{\partial \beta_i} \sum_{k=1}^n (y_k - X_{k1}\beta_1 - X_{k2}\beta_2 - \cdots - X_{kp}\beta_p)^2 \\ &= 2 \sum_{k=1}^n (y_k - X_{k1}\beta_1 - X_{k2}\beta_2 - \cdots - X_{kp}\beta_p) \times (-X_{ki}) \end{aligned}$$

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Therefore,

$$\sum_{k=1}^n X_{ki}(X_{k1}\beta_1 + X_{k2}\beta_2 + \cdots + X_{kp}\beta_p) = \sum_{k=1}^n X_{ki}y_k$$

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is equivalent to:

$$X^T X \beta = X^T y \quad (\text{Normal equations}).$$

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- Proved by computing the Hessian matrix:

$$\frac{\partial^2}{\partial \beta_i \partial \beta_j} \|Y - X\beta\|^2 = 2X^T X.$$

Linear algebra approach

Want to solve $Y = X\beta$.

Linear algebra approach: Recall: If $V \subset \mathbb{R}^n$ is a subspace and $w \notin V$, then the best approximation of w by a vector in V is

$$\text{proj}_V(w).$$

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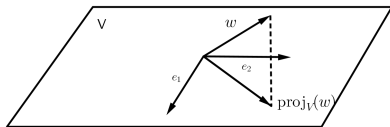
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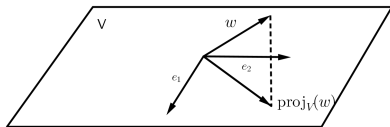
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• Note:

$$X\beta \in \text{col}(X) = \text{span}(\mathbf{x}_1, \dots, \mathbf{x}_p).$$

• If $Y \notin \text{col}(X)$, then the best approximation of Y by a vector in $\text{col}(X)$ is

$$\text{proj}_{\text{col}(X)}(Y).$$

So
$$\|Y - \text{proj}_{\text{col}(X)}(Y)\| \leq \|Y - X\beta\| \quad \forall \beta \in \mathbb{R}^p.$$

Linear algebra approach (cont.)

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(Note: this system always has a solution.)

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Equivalently,

$$X^T X \hat{\beta} = X^T Y \quad (\text{Normal equations}).$$

Theorem (Least squares theorem)

Let $A \in \mathbb{R}^{n \times m}$ and $b \in \mathbb{R}^n$. Then

- 1 $Ax = b$ always has a least squares solution \hat{x} .
- 2 A vector \hat{x} is a least squares solution iff it satisfies the normal equations

$$A^T A \hat{x} = A^T b.$$

- 3 \hat{x} is unique \Leftrightarrow the columns of A are linearly independent $\Leftrightarrow A^T A$ is invertible. In that case, the unique least squares solution is given by

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In R:

```
model <- lm(Y ~ X1 + X2 + ... + Xp).
```

How good is our linear model?

- We examine the *mean squared error*:

$$\text{MSE}(\hat{\beta}) = \frac{1}{n} \|y - X\hat{\beta}\|^2 = \frac{1}{n} \sum_{k=1}^n (y_i - \hat{y}_i)^2.$$

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- Example:

```
model <- lm(Auto$mpg ~ Auto$horsepower + Auto$weight)
sm <- summary(model)
mean(sm$residuals^2) # The MSE
```

The coefficient of determination

- The *coefficient of determination*, called “R squared” and denoted R^2 :

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- In R: `sm$r.squared`. (As above, `sm <- summary(model)`).

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- Often used to measure the quality of a linear model.
- In some sense, the R^2 measures “how much better” is the prediction, compared to a constant prediction equal to the average of the y_i s.
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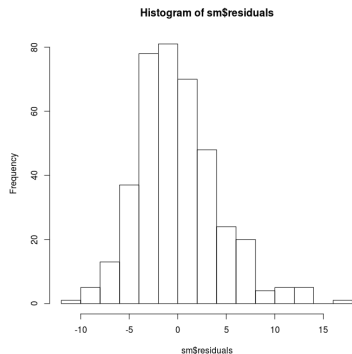
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- In a linear model with an intercept, R^2 equals the square of the correlation coefficient between the observed Y and the predicted values \hat{Y} .
- A model with a R^2 close to 1 fits the data well.

Measuring the fit of a linear model (cont.)

We can examine the distribution of the residuals:

```
hist(sm$residuals)
```



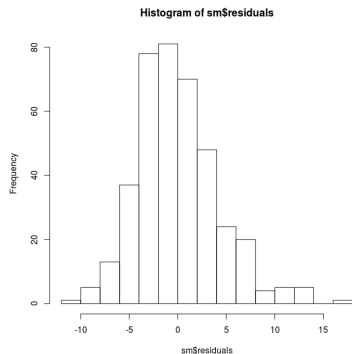
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- Symmetry
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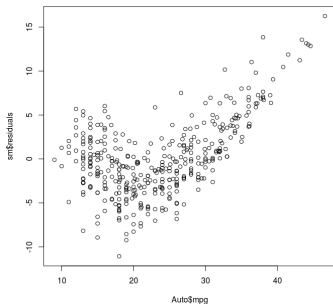


Desirable properties:

- Symmetry
 - Light tail.
- A heavy tail suggests there may be outliers.
 - Can use transformations such as \log , $\sqrt{\cdot}$, or $1/x$ to improve the fit.

Measuring the fit of a linear model (cont.)

Plotting the residuals as a function of the mpg (or fitted values), we immediately observe some patterns.



Outliers? Separate categories of cars?

Improving the model

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- Use transformations.
- Separate cars into categories.
- etc.

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For example, let us fit a model only for cars with a mpg less than 25:

