Distribution of regression coefficients

MATH 829: Introduction to Data Mining and Analysis Consistency of Linear Regression

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Observations $Y = (y_i) \in \mathbb{R}^n$, $X = (x_{ij}) \in \mathbb{R}^{n \times p}$. Assumptions: $y = \beta_1 X_{i,1} + \dots + \beta_p X_{i,p} + \epsilon_i$ ($\epsilon_i = \operatorname{error}$). In other words: $Y = X\beta + \epsilon$. ($\beta = (\beta_1, \dots, \beta_p)$ is a fixed unknown vector) $\mathbf{0}_{-\mathbf{i}_i}$ are non-random ϵ_i are random. $\mathbf{0}_{-\mathbf{i}_i}$ are independent $N(0, \sigma^2)$. We have $\hat{\beta} = (X^T X)^{-1} X^T Y$. What is the distribution of $\hat{\beta}$?

2/9

Multivariate normal distribution

Recall: $X = (X_1, \ldots, X_p) \sim N(\mu, \Sigma)$ where $\mu \in \mathbb{R}^n$, $\delta \Sigma = (\sigma_{ij}) \in \mathbb{R}^{p \times p}$ is positive definite, if $P(X \in A) = \frac{1}{\sqrt{(2\pi)^p \det \Sigma}} \int_A e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)} dx_1 \dots dx_p.$ Bivariate case: We have $E(X) = \mu, \quad Cov(X_i, X_j) = \sigma_{ij}.$ If Y = c + BX, where $c \in \mathbb{R}^p$ and $B \in \mathbb{R}^{m \times p}$, then $Y \sim N(c + B_A, BSB^T).$

Distribution of the regression coefficients (cont.)

Back to our problem: $Y=X\beta+\epsilon$ where ϵ_i are iid $N(0,\sigma^2).$ We have

$$Y \sim N(X\beta, \sigma^2 I).$$

Therefore,

$$\hat{\beta} = (X^T X)^{-1} X^T Y \sim N(\beta, \sigma^2 (X^T X)^{-1}).$$

In particular,

 $E(\hat{\beta}) = \beta.$

Thus, $\hat{\beta}$ is unbiased.

1.9

Statistical consistency of least squares

- We saw that $E(\hat{\beta}) = \beta$.
- What happens as the sample size n goes to infinity? We expect β̂ = β̂(n) → β.

A sequence of estimators $\{\theta_n\}_{n=1}^{\infty}$ of a parameter θ is said to be **consistent** if $\theta_n \to \theta$ in probability $(\theta_n \xrightarrow{p} \theta)$ as $n \to \infty$. (Recall: $\theta_n \xrightarrow{p} \theta$ if for every $\epsilon > 0$

$$\lim_{n\to\infty} P(|\theta_n - \theta| \ge \epsilon) = 0$$

In order to prove that $\hat{\beta}_n$ (estimator with n samples) is consistent, we will make some assumptions on the *data generating model*. (Without any assumptions, nothing prevents the observations to be all the same for example...)

\$/9

Background for the proof

Recall:

Weak law of large numbers: Let $(X_i)_{i=1}^\infty$ be iid random variables with finite first moment $E(|X_i|)<\infty.$ Let $\mu:=E(X_i).$ Then

$$\overline{X}_n := \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{p} \mu$$

Continuous mapping theorem: Let S, S' be metric spaces. Suppose $(X_i)_{i=1}^{N}$ are S-valued random variables such that $X_i \xrightarrow{P} X_i$. Let $g: S \to S'$. Denote by D_g the set of points in S where g is discontinuous and suppose $P(X \in D_g) = 0$. Then $g(X_n) \xrightarrow{P} g(X)$.

Statistical consistency of least squares (cont.)

 $\begin{array}{ll} \textbf{O} \text{ bservations: } y=(y_i)\in\mathbb{R}^n, X=(x_{ij})\in\mathbb{R}^{n\times p}. \text{ Let}\\ \mathbf{x}_i:=(x_{i,1},\ldots,x_{i,n})\in\mathbb{R}^p \qquad (i=1,\ldots,n).\\ \text{We will assume:} \end{array}$

- $(\mathbf{x}_i)_{i=1}^n$ are iid random vectors.
- $y_i = \beta_1 x_{i,1} + \dots + \beta_p x_{i,p} + \epsilon_i$ where ϵ_i are iid $N(0, \sigma^2)$.
- The error e_i is independent of x_i.
- $Ex_{ii}^2 < \infty$ (finite second moment).
- $\mathbf{Q} = E(\mathbf{x}_i \mathbf{x}_i^T) \in \mathbb{R}^{p \times p}$ is invertible

Under these assumptions, we have the following theorem. Theorem: Let $\hat{\beta}_n=(X^TX)^{-1}X^Ty.$ Then, under the above assumptions, we have

 $\hat{\beta}_n \xrightarrow{p} \beta$.

6/9

Proof of the theorem

We have

$$\hat{\beta} = (X^T X)^{-1} X^T y = \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T\right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i y_i\right).$$

Using Cauchy-Schwarz,

$$E(|x_{ij}x_{ik}|) \le (E(x_{ij}^2)E(x_{ik}^2))^{1/2} < \infty.$$

In a similar way, we prove that $E(|x_{ij}y_i|) < \infty$. By the weak law of large numbers, we obtain

$$\frac{1}{n}\sum_{i=1}^{n} \mathbf{x}_{i}\mathbf{x}_{i}^{T} \xrightarrow{p} E(\mathbf{x}_{i}\mathbf{x}_{i}^{T}) = Q$$

$$\frac{1}{n}\sum_{i=1}^{n} \mathbf{x}_{i}y_{i} \xrightarrow{p} E(\mathbf{x}_{i}y_{i}).$$

Using the continuous mapping theorem, we obtain

$$\begin{split} \hat{\beta}_n \stackrel{p}{\to} E(\mathbf{x}_i\mathbf{x}_i^T)^{-1}E(\mathbf{x}_iy_i). \\ (\text{define } g: \mathbb{R}^{p\times p}\times \mathbb{R}^p \to \mathbb{R}^p \text{ by } g(A,b) = A^{-1}b.) \\ \text{Recall: } y_i = \mathbf{x}_i^T\beta + \epsilon_i. \text{ So} \end{split}$$

$$\mathbf{x}_i y_i = \mathbf{x}_i \mathbf{x}_i^T \beta + \mathbf{x}_i \epsilon_i$$
.

Taking expectations,

$$E(\mathbf{x}_i y_i) = E(\mathbf{x}_i \mathbf{x}_i^T)\beta + E(\mathbf{x}_i \epsilon_i).$$

Note that $E(\mathbf{x}_i \epsilon_i) = 0$ since \mathbf{x}_i and ϵ_i are independent by assumption.

We conclude that

$$\beta = E(\mathbf{x}_i \mathbf{x}_i^T)^{-1} E(\mathbf{x}_i y_i)$$

and so $\hat{\beta}_n \xrightarrow{p} \beta$.

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