

# MATH 829: Introduction to Data Mining and Analysis Clustering II

Dominique Guillot

Departments of Mathematical Sciences  
University of Delaware

April 27, 2016

# Spectral clustering: overview

In the previous lecture, we discussed how  $K$ -means can be used to cluster points in  $\mathbb{R}^p$ .

Spectral clustering:

- Very popular clustering method.
- Often outperforms other methods such as  $K$ -means.
- Can be used for various “types” of data (not only points in  $\mathbb{R}^p$ ).
- Easy to implement. Only uses basic linear algebra.

# Spectral clustering: overview

In the previous lecture, we discussed how  $K$ -means can be used to cluster points in  $\mathbb{R}^p$ .

Spectral clustering:

- Very popular clustering method.
- Often outperforms other methods such as  $K$ -means.
- Can be used for various “types” of data (not only points in  $\mathbb{R}^p$ ).
- Easy to implement. Only uses basic linear algebra.

Overview of spectral clustering:

# Spectral clustering: overview

In the previous lecture, we discussed how  $K$ -means can be used to cluster points in  $\mathbb{R}^p$ .

Spectral clustering:

- Very popular clustering method.
- Often outperforms other methods such as  $K$ -means.
- Can be used for various “types” of data (not only points in  $\mathbb{R}^p$ ).
- Easy to implement. Only uses basic linear algebra.

Overview of spectral clustering:

- 1 Construct a *similarity matrix* measuring the similarity of pairs of objects.

# Spectral clustering: overview

In the previous lecture, we discussed how  $K$ -means can be used to cluster points in  $\mathbb{R}^p$ .

Spectral clustering:

- Very popular clustering method.
- Often outperforms other methods such as  $K$ -means.
- Can be used for various “types” of data (not only points in  $\mathbb{R}^p$ ).
- Easy to implement. Only uses basic linear algebra.

Overview of spectral clustering:

- 1 Construct a *similarity matrix* measuring the similarity of pairs of objects.
- 2 Use the similarity matrix to construct a (weighted or unweighted) graph.

# Spectral clustering: overview

In the previous lecture, we discussed how  $K$ -means can be used to cluster points in  $\mathbb{R}^p$ .

Spectral clustering:

- Very popular clustering method.
- Often outperforms other methods such as  $K$ -means.
- Can be used for various “types” of data (not only points in  $\mathbb{R}^p$ ).
- Easy to implement. Only uses basic linear algebra.

Overview of spectral clustering:

- 1 Construct a *similarity matrix* measuring the similarity of pairs of objects.
- 2 Use the similarity matrix to construct a (weighted or unweighted) graph.
- 3 Compute eigenvectors of the *graph Laplacian*.

# Spectral clustering: overview

In the previous lecture, we discussed how  $K$ -means can be used to cluster points in  $\mathbb{R}^p$ .

Spectral clustering:

- Very popular clustering method.
- Often outperforms other methods such as  $K$ -means.
- Can be used for various “types” of data (not only points in  $\mathbb{R}^p$ ).
- Easy to implement. Only uses basic linear algebra.

Overview of spectral clustering:

- 1 Construct a *similarity matrix* measuring the similarity of pairs of objects.
- 2 Use the similarity matrix to construct a (weighted or unweighted) graph.
- 3 Compute eigenvectors of the *graph Laplacian*.
- 4 Cluster the graph using the eigenvectors of the graph Laplacian using the  $K$ -means algorithm.

We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .



We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .
- Each edge carries a *weight*  $w_{ij} \geq 0$ .

We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .
- Each edge carries a *weight*  $w_{ij} \geq 0$ .
- The adjacency matrix of  $G$  is  $W = W_G = (w_{ij})_{i,j=1}^n$ . We will assume  $W$  is symmetric (undirected graphs).

We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .
- Each edge carries a *weight*  $w_{ij} \geq 0$ .
- The adjacency matrix of  $G$  is  $W = W_G = (w_{ij})_{i,j=1}^n$ . We will assume  $W$  is symmetric (undirected graphs).
- The *degree* of  $v_i$  is

$$d_i := \sum_{j=1}^n w_{ij}.$$

We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .
- Each edge carries a *weight*  $w_{ij} \geq 0$ .
- The adjacency matrix of  $G$  is  $W = W_G = (w_{ij})_{i,j=1}^n$ . We will assume  $W$  is symmetric (undirected graphs).

- The *degree* of  $v_i$  is

$$d_i := \sum_{j=1}^n w_{ij}.$$

- The *degree matrix* of  $G$  is  $D := \text{diag}(d_1, \dots, d_n)$ .

We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .
- Each edge carries a *weight*  $w_{ij} \geq 0$ .
- The adjacency matrix of  $G$  is  $W = W_G = (w_{ij})_{i,j=1}^n$ . We will assume  $W$  is symmetric (undirected graphs).

- The *degree* of  $v_i$  is

$$d_i := \sum_{j=1}^n w_{ij}.$$

- The *degree matrix* of  $G$  is  $D := \text{diag}(d_1, \dots, d_n)$ .
- We denote the complement of  $A \subset V$  by  $\bar{A}$ .

We will use the following notation/conventions:

- $G = (V, E)$  a graph with vertex set  $V = \{v_1, \dots, v_n\}$  and edge set  $E \subset V \times V$ .
- Each edge carries a *weight*  $w_{ij} \geq 0$ .
- The adjacency matrix of  $G$  is  $W = W_G = (w_{ij})_{i,j=1}^n$ . We will assume  $W$  is symmetric (undirected graphs).

- The *degree* of  $v_i$  is

$$d_i := \sum_{j=1}^n w_{ij}.$$

- The *degree matrix* of  $G$  is  $D := \text{diag}(d_1, \dots, d_n)$ .
- We denote the complement of  $A \subset V$  by  $\bar{A}$ .
- If  $A \subset V$ , then we let  $\mathbb{1}_A = (f_1, \dots, f_n)^T \in \mathbb{R}^n$ , where  $f_i = 1$  if  $v_i \in A$  and 0 otherwise.

# Similarity graphs

- We assume we are given a measure of similarity  $s$  between data points  $x_1, \dots, x_n \in \mathcal{X}$ :

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We assume we are given a measure of similarity  $s$  between data points  $x_1, \dots, x_n \in \mathcal{X}$ :

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We denote by  $s_{ij} := s(x_i, x_j)$  the *measure of similarity* between  $x_i$  and  $x_j$ .



# Similarity graphs

- We assume we are given a measure of similarity  $s$  between data points  $x_1, \dots, x_n \in \mathcal{X}$ :

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We denote by  $s_{ij} := s(x_i, x_j)$  the *measure of similarity* between  $x_i$  and  $x_j$ .
- Equivalently, we may assume we have a measure of *distance* between data points (e.g.  $(\mathcal{X}, d)$  is a metric space).

- We assume we are given a measure of similarity  $s$  between data points  $x_1, \dots, x_n \in \mathcal{X}$ :

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We denote by  $s_{ij} := s(x_i, x_j)$  the *measure of similarity* between  $x_i$  and  $x_j$ .
- Equivalently, we may assume we have a measure of *distance* between data points (e.g.  $(\mathcal{X}, d)$  is a metric space).
- Let  $d_{ij} := d(x_i, x_j)$ , the distance between  $x_i$  and  $x_j$ .

# Similarity graphs

- We assume we are given a measure of similarity  $s$  between data points  $x_1, \dots, x_n \in \mathcal{X}$ :

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We denote by  $s_{ij} := s(x_i, x_j)$  the *measure of similarity* between  $x_i$  and  $x_j$ .
- Equivalently, we may assume we have a measure of *distance* between data points (e.g.  $(\mathcal{X}, d)$  is a metric space).
- Let  $d_{ij} := d(x_i, x_j)$ , the distance between  $x_i$  and  $x_j$ .
- From  $d_{ij}$  (or  $s_{ij}$ ), we naturally build a *similarity graph*.

# Similarity graphs

- We assume we are given a measure of similarity  $s$  between data points  $x_1, \dots, x_n \in \mathcal{X}$ :

$$s : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty).$$

- We denote by  $s_{ij} := s(x_i, x_j)$  the *measure of similarity* between  $x_i$  and  $x_j$ .
- Equivalently, we may assume we have a measure of *distance* between data points (e.g.  $(\mathcal{X}, d)$  is a metric space).
- Let  $d_{ij} := d(x_i, x_j)$ , the distance between  $x_i$  and  $x_j$ .
- From  $d_{ij}$  (or  $s_{ij}$ ), we naturally build a *similarity graph*.
- We will discuss 3 popular ways of building a similarity graph.

## Similarity graphs (cont.)

Vertex set =  $\{v_1, \dots, v_n\}$  where  $n$  is the number of data points.

## Similarity graphs (cont.)

Vertex set =  $\{v_1, \dots, v_n\}$  where  $n$  is the number of data points.

- 1 **The  $\epsilon$ -neighborhood graph:** Connect all points whose pairwise distances are smaller than some  $\epsilon > 0$ . We usually don't weight the edges. The graph is thus a simple graph (unweighted, undirected graph containing no loops or multiple edges).

## Similarity graphs (cont.)

Vertex set =  $\{v_1, \dots, v_n\}$  where  $n$  is the number of data points.

- 1 **The  $\epsilon$ -neighborhood graph:** Connect all points whose pairwise distances are smaller than some  $\epsilon > 0$ . We usually don't weight the edges. The graph is thus a simple graph (unweighted, undirected graph containing no loops or multiple edges).
- 2 **The  $k$ -nearest neighbor graph:** The goal is to connect  $v_i$  to  $v_j$  if  $x_j$  is among the  $k$  nearest neighbors of  $x_i$ . However, this leads to a directed graph. We therefore define:

## Similarity graphs (cont.)

Vertex set =  $\{v_1, \dots, v_n\}$  where  $n$  is the number of data points.

- 1 **The  $\epsilon$ -neighborhood graph:** Connect all points whose pairwise distances are smaller than some  $\epsilon > 0$ . We usually don't weight the edges. The graph is thus a simple graph (unweighted, undirected graph containing no loops or multiple edges).
- 2 **The  $k$ -nearest neighbor graph:** The goal is to connect  $v_i$  to  $v_j$  if  $x_j$  is among the  $k$  nearest neighbors of  $x_i$ . However, this leads to a directed graph. We therefore define:
  - the  $k$ -nearest neighbor graph:  $v_i$  is adjacent to  $v_j$  iff  $x_j$  is among the  $k$  nearest neighbors of  $x_i$  **OR**  $x_i$  is among the  $k$  nearest neighbors of  $x_j$ .



# Similarity graphs (cont.)

Vertex set =  $\{v_1, \dots, v_n\}$  where  $n$  is the number of data points.

- 1 **The  $\epsilon$ -neighborhood graph:** Connect all points whose pairwise distances are smaller than some  $\epsilon > 0$ . We usually don't weight the edges. The graph is thus a simple graph (unweighted, undirected graph containing no loops or multiple edges).
- 2 **The  $k$ -nearest neighbor graph:** The goal is to connect  $v_i$  to  $v_j$  if  $x_j$  is among the  $k$  nearest neighbors of  $x_i$ . However, this leads to a directed graph. We therefore define:
  - the  $k$ -nearest neighbor graph:  $v_i$  is adjacent to  $v_j$  iff  $x_j$  is among the  $k$  nearest neighbors of  $x_i$  **OR**  $x_i$  is among the  $k$  nearest neighbors of  $x_j$ .
  - the mutual  $k$ -nearest neighbor graph:  $v_i$  is adjacent to  $v_j$  iff  $x_j$  is among the  $k$  nearest neighbors of  $x_i$  **AND**  $x_i$  is among the  $k$  nearest neighbors of  $x_j$ .

# Similarity graphs (cont.)

Vertex set =  $\{v_1, \dots, v_n\}$  where  $n$  is the number of data points.

- 1 **The  $\epsilon$ -neighborhood graph:** Connect all points whose pairwise distances are smaller than some  $\epsilon > 0$ . We usually don't weight the edges. The graph is thus a simple graph (unweighted, undirected graph containing no loops or multiple edges).
- 2 **The  $k$ -nearest neighbor graph:** The goal is to connect  $v_i$  to  $v_j$  if  $x_j$  is among the  $k$  nearest neighbors of  $x_i$ . However, this leads to a directed graph. We therefore define:
  - the  $k$ -nearest neighbor graph:  $v_i$  is adjacent to  $v_j$  iff  $x_j$  is among the  $k$  nearest neighbors of  $x_i$  **OR**  $x_i$  is among the  $k$  nearest neighbors of  $x_j$ .
  - the mutual  $k$ -nearest neighbor graph:  $v_i$  is adjacent to  $v_j$  iff  $x_j$  is among the  $k$  nearest neighbors of  $x_i$  **AND**  $x_i$  is among the  $k$  nearest neighbors of  $x_j$ .

We weight the edges by the similarity of their endpoints.

- ③ **The fully connected graph:** Connect all points with edge weights  $s_{ij}$ .

- ③ **The fully connected graph:** Connect all points with edge weights  $s_{ij}$ . For example, one could use the *Gaussian similarity function* to represent a local neighborhood relationships:

$$s_{ij} = s(x_i, x_j) = \exp(-\|x_i - x_j\|^2 / (2\sigma^2)) \quad (\sigma^2 > 0).$$

Note:  $\sigma^2$  controls the width of the neighborhoods.

- ③ **The fully connected graph:** Connect all points with edge weights  $s_{ij}$ . For example, one could use the *Gaussian similarity function* to represent a local neighborhood relationships:

$$s_{ij} = s(x_i, x_j) = \exp(-\|x_i - x_j\|^2 / (2\sigma^2)) \quad (\sigma^2 > 0).$$

Note:  $\sigma^2$  controls the width of the neighborhoods.

All graphs mentioned above are regularly used in spectral clustering.

There are three commonly used definitions of the graph Laplacian:

- 1 **The unnormalized Laplacian** is

$$L := D - W.$$

There are three commonly used definitions of the graph Laplacian:

- 1 **The unnormalized Laplacian** is

$$L := D - W.$$

- 2 **The normalized symmetric Laplacian** is

$$L_{\text{sym}} := D^{-1/2} L D^{-1/2} = I - D^{-1/2} W D^{-1/2}.$$

There are three commonly used definitions of the graph Laplacian:

- 1 **The unnormalized Laplacian** is

$$L := D - W.$$

- 2 **The normalized symmetric Laplacian** is

$$L_{\text{sym}} := D^{-1/2}LD^{-1/2} = I - D^{-1/2}WD^{-1/2}.$$

- 3 **The normalized “random walk” Laplacian** is

$$L_{\text{rw}} := D^{-1}L = I - D^{-1}W.$$



There are three commonly used definitions of the graph Laplacian:

- 1 **The unnormalized Laplacian** is

$$L := D - W.$$

- 2 **The normalized symmetric Laplacian** is

$$L_{\text{sym}} := D^{-1/2}LD^{-1/2} = I - D^{-1/2}WD^{-1/2}.$$

- 3 **The normalized “random walk” Laplacian** is

$$L_{\text{rw}} := D^{-1}L = I - D^{-1}W.$$

We begin by studying properties of the *unnormalized Laplacian*.

# The unnormalized Laplacian

**Proposition:** The matrix  $L$  satisfies the following properties:

# The unnormalized Laplacian

**Proposition:** The matrix  $L$  satisfies the following properties:

- 1 For any  $f \in \mathbb{R}^n$ :

$$f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2.$$

# The unnormalized Laplacian

**Proposition:** The matrix  $L$  satisfies the following properties:

- 1 For any  $f \in \mathbb{R}^n$ :

$$f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2.$$

- 2  $L$  is symmetric and positive semidefinite.

# The unnormalized Laplacian

**Proposition:** The matrix  $L$  satisfies the following properties:

- 1 For any  $f \in \mathbb{R}^n$ :

$$f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2.$$

- 2  $L$  is symmetric and positive semidefinite.
- 3 0 is an eigenvalue of  $L$  with associated constant eigenvector  $\mathbb{1}$ .

# The unnormalized Laplacian

**Proposition:** The matrix  $L$  satisfies the following properties:

- 1 For any  $f \in \mathbb{R}^n$ :

$$f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2.$$

- 2  $L$  is symmetric and positive semidefinite.
- 3 0 is an eigenvalue of  $L$  with associated constant eigenvector  $\mathbb{1}$ .

**Proof:**

# The unnormalized Laplacian

**Proposition:** The matrix  $L$  satisfies the following properties:

① For any  $f \in \mathbb{R}^n$ :

$$f^T L f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2.$$

②  $L$  is symmetric and positive semidefinite.

③ 0 is an eigenvalue of  $L$  with associated constant eigenvector  $\mathbb{1}$ .

**Proof:** To prove (1),

$$\begin{aligned} f^T L f &= f^T D f - f^T W f = \sum_{i=1}^n d_i f_i^2 - \sum_{i,j=1}^n w_{ij} f_i f_j \\ &= \frac{1}{2} \left( \sum_{i=1}^n d_i f_i^2 - 2 \sum_{i,j=1}^n w_{ij} f_i f_j + \sum_{j=1}^n d_j f_j^2 \right) \\ &= \frac{1}{2} \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2. \end{aligned}$$

(2) follows from (1). (3) is easy. □

## The unnormalized Laplacian (cont.)

**Proposition:** Let  $G$  be an undirected graph with non-negative weights. Then:



# The unnormalized Laplacian (cont.)

**Proposition:** Let  $G$  be an undirected graph with non-negative weights. Then:

- 1 The multiplicity  $k$  of the eigenvalue 0 of  $L$  equals the number of connected components  $A_1, \dots, A_k$  in the graph.

# The unnormalized Laplacian (cont.)

**Proposition:** Let  $G$  be an undirected graph with non-negative weights. Then:

- 1 The multiplicity  $k$  of the eigenvalue 0 of  $L$  equals the number of connected components  $A_1, \dots, A_k$  in the graph.
- 2 The eigenspace of eigenvalue 0 is spanned by the indicator vectors  $\mathbb{1}_{A_1}, \dots, \mathbb{1}_{A_k}$  of those components.

# The unnormalized Laplacian (cont.)

**Proposition:** Let  $G$  be an undirected graph with non-negative weights. Then:

- 1 The multiplicity  $k$  of the eigenvalue 0 of  $L$  equals the number of connected components  $A_1, \dots, A_k$  in the graph.
- 2 The eigenspace of eigenvalue 0 is spanned by the indicator vectors  $\mathbb{1}_{A_1}, \dots, \mathbb{1}_{A_k}$  of those components.

**Proof:**

# The unnormalized Laplacian (cont.)

**Proposition:** Let  $G$  be an undirected graph with non-negative weights. Then:

- 1 The multiplicity  $k$  of the eigenvalue 0 of  $L$  equals the number of connected components  $A_1, \dots, A_k$  in the graph.
- 2 The eigenspace of eigenvalue 0 is spanned by the indicator vectors  $\mathbb{1}_{A_1}, \dots, \mathbb{1}_{A_k}$  of those components.

**Proof:** If  $f$  is an eigenvector associate to  $\lambda = 0$ , then

$$0 = f^T L f = \sum_{i,j=1}^n w_{ij} (f_i - f_j)^2.$$

It follows that  $f_i = f_j$  whenever  $w_{ij} > 0$ . Thus  $f$  is constant on the connected components of  $G$ . We conclude that the eigenspace of 0 is contained in  $\text{span}(\mathbb{1}_{A_1}, \dots, \mathbb{1}_{A_k})$ . Conversely, it is not hard to see that each  $\mathbb{1}_{A_i}$  is an eigenvector associated to 0 (write  $L$  in block diagonal form). □

**Proposition:** The normalized Laplacians satisfy the following properties:

- 1 For every  $f \in \mathbb{R}^n$ , we have

$$f^T L_{\text{sym}} f = \frac{1}{2} \sum_{i,j=1}^n w_{ij} \left( \frac{f_i}{\sqrt{d_i}} - \frac{f_j}{\sqrt{d_j}} \right)^2.$$

- 2  $\lambda$  is an eigenvalue of  $L_{\text{rw}}$  with eigenvector  $u$  if and only if  $\lambda$  is an eigenvalue of  $L_{\text{sym}}$  with eigenvector  $w = D^{1/2}u$ .
- 3  $\lambda$  is an eigenvalue of  $L_{\text{rw}}$  with eigenvector  $u$  if and only if  $\lambda$  and  $u$  solve the generalized eigenproblem  $Lu = \lambda Du$ .

**Proof:** The proof of (1) is similar to the proof of the analogous result for the unnormalized Laplacian. (2) and (3) follow easily by using appropriate rescalings.

**Proposition:** Let  $G$  be an undirected graph with non-negative weights. Then:

- 1 The multiplicity  $k$  of the eigenvalue 0 of both  $L_{\text{sym}}$  and  $L_{\text{rw}}$  equals the number of connected components  $A_1, \dots, A_k$  in the graph.
- 2 For  $L_{\text{rw}}$ , the eigenspace of eigenvalue 0 is spanned by the indicator vectors  $\mathbb{1}_{A_i}$ ,  $i = 1, \dots, k$ .
- 3 For  $L_{\text{sym}}$ , the eigenspace of eigenvalue 0 is spanned by the vectors  $D^{1/2} \mathbb{1}_{A_i}$ ,  $i = 1, \dots, k$ .

**Proof:** Similar to the proof of the analogous result for the unnormalized Laplacian.